

In [1]:

```
# Importing libraries

import numpy as np
import zipfile
import pandas as pd
import seaborn as sns
import matplotlib.pyplot as plt

import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers
from tensorflow.keras.layers import Dropout
from tensorflow.keras import callbacks
from keras.callbacks import ModelCheckpoint, TensorBoard
from keras.callbacks import EarlyStopping

# Clustering
from sklearn.decomposition import PCA
from sklearn.cluster import KMeans
from sklearn.metrics import silhouette_score
from sklearn import mixture

# 3D Visualization
import plotly.express as px
import plotly as py
import plotly.graph_objs as go
```

In [2]:

```
from sklearn.preprocessing import StandardScaler
from sklearn.model_selection import ShuffleSplit, train_test_split
from sklearn.metrics import confusion_matrix, precision_recall_curve
from sklearn.metrics import recall_score, classification_report, auc, roc_curve
from sklearn.metrics import precision_recall_fscore_support, f1_score

from numpy.random import seed
seed(7)
from tensorflow.random import set_seed
set_seed(11)
from sklearn.model_selection import train_test_split

SEED = 123 #used to help randomly select the data points
DATA_SPLIT_PCT = 0.2
```

In [3]:

```
df = pd.read_csv('sensor.csv')
```

In [4]:

```
# consider that sensor was having an issue and its giving the same reading for these tim
# I used forward fill propagation as a method of dealing with missing values

df.fillna(method = 'ffill' , inplace = True)
```

In [5]:

```
df.head()
```

Out[5]:

	Unnamed: 0	timestamp	sensor_00	sensor_01	sensor_02	sensor_03	sensor_04	sensor_0
0	0	2018-04-01 00:00:00	2.465394	47.09201	53.2118	46.310760	634.3750	76.4597
1	1	2018-04-01 00:01:00	2.465394	47.09201	53.2118	46.310760	634.3750	76.4597
2	2	2018-04-01 00:02:00	2.444734	47.35243	53.2118	46.397570	638.8889	73.5459
3	3	2018-04-01 00:03:00	2.460474	47.09201	53.1684	46.397568	628.1250	76.9889
4	4	2018-04-01 00:04:00	2.445718	47.13541	53.2118	46.397568	636.4583	76.5889

5 rows × 55 columns

In [6]:

```
#Locate indices of failure events and recovering and normal state
df_n = df.loc[df['machine_status'] == 'NORMAL'].copy()
df_b = df.loc[df['machine_status'] == 'BROKEN'].copy()
df_r = df.loc[df['machine_status'] == 'RECOVERING'].copy()

df_n.index = df_n.timestamp
df_b.index = df_b.timestamp
df_r.index = df_r.timestamp
```

In [7]:

```
df_n.drop(columns=['Unnamed: 0', 'timestamp', 'machine_status', 'sensor_51', 'sensor_15'],
df_b.drop(columns=['Unnamed: 0', 'timestamp', 'machine_status', 'sensor_51', 'sensor_15'],
df_r.drop(columns=['Unnamed: 0', 'timestamp', 'machine_status', 'sensor_51', 'sensor_15'],
df_n.head()
```

Out[7]:

In [8]:

```
df_n.describe()
```

Out[8]:

	sensor_00	sensor_01	sensor_02	sensor_03	sensor_04	sens
count	205836.000000	205836.000000	205836.000000	205836.000000	205836.000000	205836.000000
mean	2.420479	48.186489	51.636921	44.167010	625.673663	75.3
std	0.242464	2.247538	1.878258	1.668233	50.820977	9.3
min	0.000000	0.000000	37.413190	33.289930	2.798032	0.0
25%	2.444734	46.701390	50.651040	43.142361	628.240700	70.5
50%	2.456539	48.263890	51.736111	44.357635	633.333313	75.6
75%	2.499826	49.565970	52.907986	45.355900	637.963000	80.6
max	2.549016	56.727430	56.032990	48.220490	800.000000	99.9

8 rows × 50 columns

Prepare data for LSTM

In [9]:

```
# First, obtain the array

input_X = df_n.values
n_features = input_X.shape[1]
```

In [10]:

```
def temporalize(X, lookback):

    ...

    Inputs
    X      A 2D numpy array ordered by time of shape:
           (n_observations x n_features)
    y      A 1D numpy array with indexes aligned with
           X, i.e. y[i] should correspond to X[i].
           Shape: n_observations.
    lookback The window size to look back in the past
             records. Shape: a scalar.

    Output
    output_X A 3D numpy array of shape:
              ((n_observations-lookback-1) x lookback x
               n_features)
    output_y A 1D array of shape:
              (n_observations-lookback-1), aligned with X.
    ...

    output_X = []

    for i in range(len(X) - lookback - 1):
        t = []
        for j in range(1, lookback + 1):
            # Gather the past records upto the Lookback period
            t.append(X[[i + j + 1]], :))
        output_X.append(t)

    return np.squeeze(np.array(output_X))
```

In [11]:

```
lookback= 5
len(input_X)-lookback-1, range(1, lookback+1)
```

Out[11]:

(205830, range(1, 6))

In [12]:

```
X = temporalize(input_X, lookback)
```

In [13]:

```
X.shape, input_X.shape  
# Samples * Lookback * features , Samples * features
```

Out[13]:

```
((205830, 5, 50), (205836, 50))
```

Train-Test Split

In [14]:

```
X_train, X_test = train_test_split(np.array(X), test_size=DATA_SPLIT_PCT, random_state=S
```

In [15]:

```
X_train.shape
```

Out[15]:

```
(164664, 5, 50)
```

Data standardization

In [16]:

```
def flatten(X):  
    ...  
    Flatten a 3D array.  
  
    Input  
    X          A 3D array for lstm, where the array is sample x timesteps x features.  
  
    Output  
    flattened_X  A 2D array, sample x features.  
    ...  
    flattened_X = np.empty((X.shape[0], X.shape[2])) # sample x features array.  
    for i in range(X.shape[0]):  
        flattened_X[i] = X[i, (X.shape[1]-1), :]  
    return(flattened_X)
```

In [17]:

```
def scale(X, scaler):
    ...
    Scale 3D array.

    Inputs
    X          A 3D array for lstm, where the array is sample x timesteps x features.
    scaler      A scaler object, e.g., sklearn.preprocessing.StandardScaler, sklearn.pr

    Output
    X          Scaled 3D array.
    ...

    for i in range(X.shape[0]):
        X[i, :, :] = scaler.transform(X[i, :, :])

    return X
```

In [18]:

```
# Initialize a scaler using the training data.
scaler = StandardScaler().fit(flatten(X_train))
```

In [19]:

```
X_train_scaled = scale(X_train, scaler)
```

In [20]:

```
a = flatten(X_train_scaled)
print('colwise mean', np.mean(a, axis=0).round(6))
print('colwise variance', np.var(a, axis=0))

colwise mean [ 0.  0.  0.  0. -0. -0.  0.  0.  0.  0.  0.  0.  0.  0. -0.  0.
0.  0.  0. -0.  0. -0. -0.  0.  0.  0. -0.  0. -0. -0. -0. -0. -0.
-0. -0.  0. -0.  0. -0.  0. -0. -0. -0. -0. -0. -0. -0. -0. -0.
0.  0.  0.  0.  0. -0. -0. -0. -0. -0. -0. -0. -0. -0. -0. -0. -0.
-0. -0. -0. -0. -0. -0. -0. -0. -0. -0. -0. -0. -0. -0. -0. -0.
0.  0.  0.  0.  0.  0.  0.  0.  0.  0.  0.  0.  0.  0.  0.  0.  0.  0.
1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.
1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.  1.
1.  1. ]
```

Building architecture

In [21]:

```
X_train_scaled.shape
```

Out[21]:

```
(164664, 5, 50)
```

In [22]:

```
timesteps = X_train_scaled.shape[1] # equal to the Lookback
n_features = X_train_scaled.shape[2] # equal to the columns

epochs = 30
batch = 64
lr = 0.0001
```

In [23]:

```
# Recurrent autoencoder

#Encoder

input_layer = keras.Input(shape=(timesteps,n_features))
encoding_layer = layers.LSTM(32, activation='tanh', return_sequences=True)(input_layer)
hidden_layer = layers.LSTM(16,activation='tanh', return_sequences=False)(encoding_layer)

compact_features = layers.RepeatVector(timesteps)(hidden_layer)

#encoder_2d = keras.Model(inputs=input_layer, outputs = compact_features)

# Decoder

decoding_1layer = layers.LSTM(32, activation='tanh', return_sequences=True)(compact_features)
decoding_2layer = layers.LSTM(40, activation='tanh', return_sequences=True)(decoding_1layer)

decoding_3layer = layers.Dense(n_features)
output_layer = layers.TimeDistributed(decoding_3layer)(decoding_2layer)

autoencoder = keras.Model(inputs=input_layer, outputs=output_layer)
autoencoder.summary()
```

Model: "model"

Layer (type)	Output Shape	Param #
<hr/>		
input_1 (InputLayer)	[(None, 5, 50)]	0
lstm (LSTM)	(None, 5, 32)	10624
lstm_1 (LSTM)	(None, 16)	3136
repeat_vector (RepeatVector)	(None, 5, 16)	0
r)		
lstm_2 (LSTM)	(None, 5, 32)	6272
lstm_3 (LSTM)	(None, 5, 40)	11680
time_distributed (TimeDistributed)	(None, 5, 50)	2050
ributed)		
<hr/>		
Total params: 33762 (131.88 KB)		
Trainable params: 33762 (131.88 KB)		
Non-trainable params: 0 (0.00 Byte)		

In [24]:

```
autoencoder.compile(loss='mse', optimizer='adam')

cp = ModelCheckpoint(filepath="lstm_autoencoder_classifier.h5",
                     save_best_only=True,
                     verbose=0)

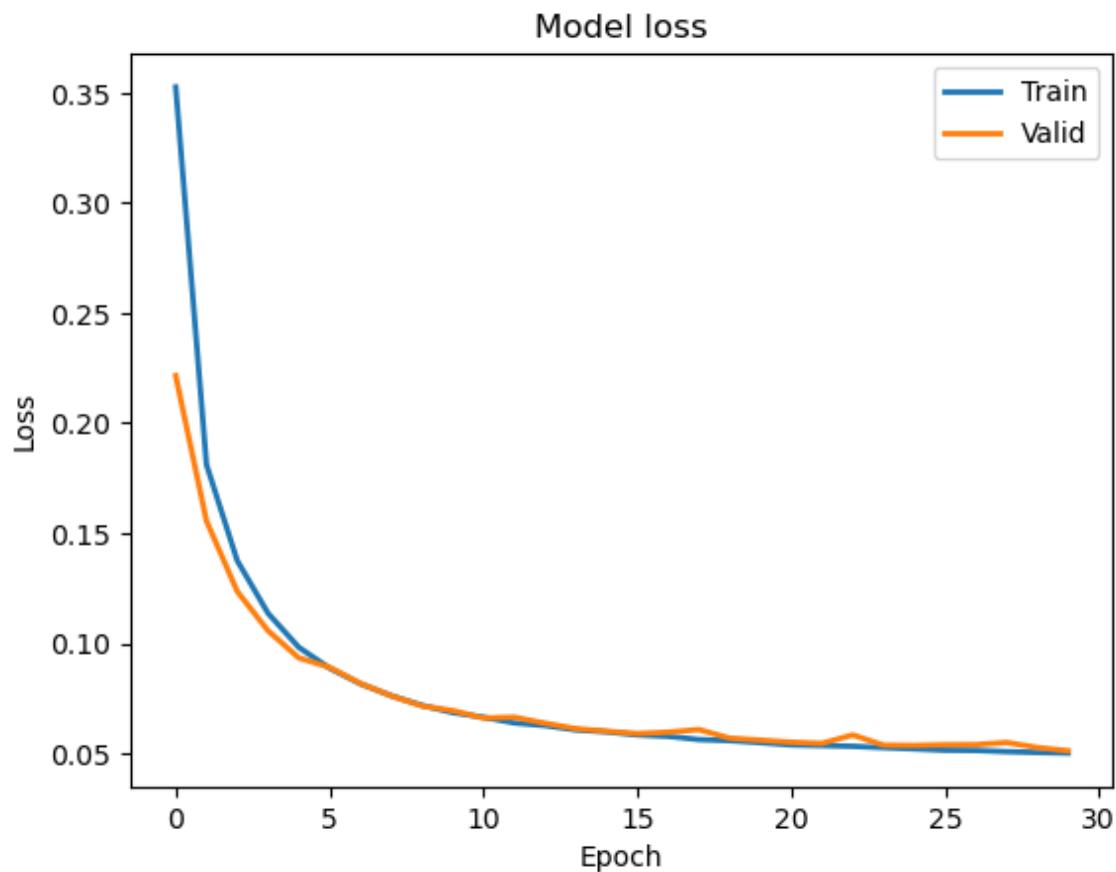
tb = TensorBoard(log_dir='./logs',
                 histogram_freq=0,
                 write_graph=True,
                 write_images=True)

lstm_autoencoder = autoencoder.fit(X_train_scaled, X_train_scaled,
                                    validation_split = 0.33,
                                    epochs = epochs,
                                    #callbacks = [E_Stop],
                                    batch_size = batch,
                                    shuffle = True,
                                    verbose=2
                                    )
```

```
Epoch 1/30
1724/1724 - 48s - loss: 0.3526 - val_loss: 0.2215 - 48s/epoch - 28ms/st
ep
Epoch 2/30
1724/1724 - 37s - loss: 0.1812 - val_loss: 0.1556 - 37s/epoch - 21ms/st
ep
Epoch 3/30
1724/1724 - 36s - loss: 0.1375 - val_loss: 0.1236 - 36s/epoch - 21ms/st
ep
Epoch 4/30
1724/1724 - 34s - loss: 0.1137 - val_loss: 0.1057 - 34s/epoch - 19ms/st
ep
Epoch 5/30
1724/1724 - 34s - loss: 0.0982 - val_loss: 0.0934 - 34s/epoch - 19ms/st
ep
Epoch 6/30
1724/1724 - 35s - loss: 0.0887 - val_loss: 0.0891 - 35s/epoch - 20ms/st
ep
Epoch 7/30
1724/1724 - 21s - loss: 0.0816 - val_loss: 0.0810 - 21s/epoch - 20ms/st
```

In [25]:

```
plt.plot(lstm_autoencoder.history['loss'], linewidth=2, label='Train')
plt.plot(lstm_autoencoder.history['val_loss'], linewidth=2, label='Valid')
plt.legend(loc='upper right')
plt.title('Model loss')
plt.ylabel('Loss')
plt.xlabel('Epoch')
plt.show()
```



Running just the Encoder

In [26]:

```
LSTM_encoder = keras.Model(inputs=input_layer, outputs = compact_features)
LSTM_encoder.summary()
```

Model: "model_1"

Layer (type)	Output Shape	Param #
input_1 (InputLayer)	[(None, 5, 50)]	0
lstm (LSTM)	(None, 5, 32)	10624
lstm_1 (LSTM)	(None, 16)	3136
repeat_vector (RepeatVector (r))	(None, 5, 16)	0

Total params: 13760 (53.75 KB)
Trainable params: 13760 (53.75 KB)
Non-trainable params: 0 (0.00 Byte)

In [27]:

```
X_test_scaled = scale(X_test, scaler)
```

In [28]:

```
Result_LSTM = LSTM_encoder.predict(X_test_scaled)
```

1287/1287 [=====] - 7s 4ms/step

In [29]:

```
Result_LSTM.shape
```

Out[29]:

(41166, 5, 16)

In [30]:

```
pca = PCA(n_components=2)
```

In [31]:

```
Result_1_LSTM = Result_LSTM.reshape(Result_LSTM.shape[0], -1)
```

In [32]:

```
Result_1_LSTM.shape
```

Out[32]:

(41166, 80)

In [33]:

```
F_Result_LSTM = pca.fit_transform(Result_1_LSTM)
```

In [34]:

```
pca.explained_variance_ratio_
```

Out[34]:

```
array([0.41728452, 0.32852784], dtype=float32)
```

In [35]:

```
F_Result_LSTM.shape
```

Out[35]:

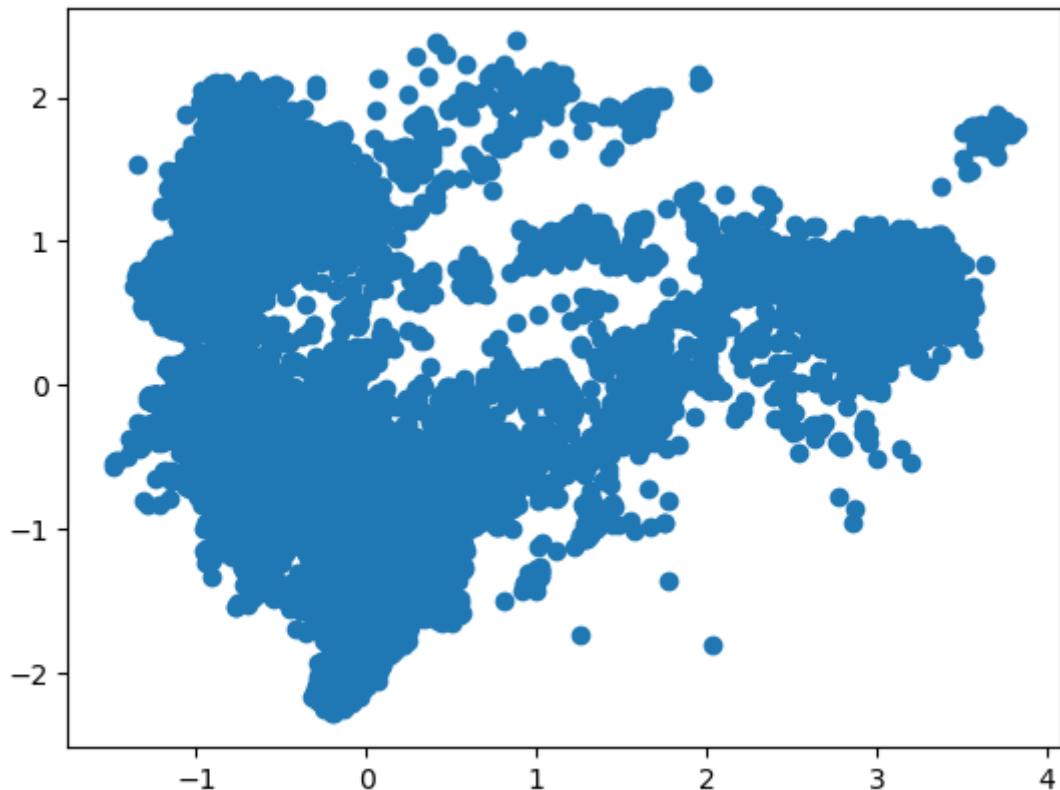
```
(41166, 2)
```

In [36]:

```
plt.scatter(x=F_Result_LSTM[:,0], y= F_Result_LSTM[:,1])
```

Out[36]:

```
<matplotlib.collections.PathCollection at 0x1b489b1cb80>
```

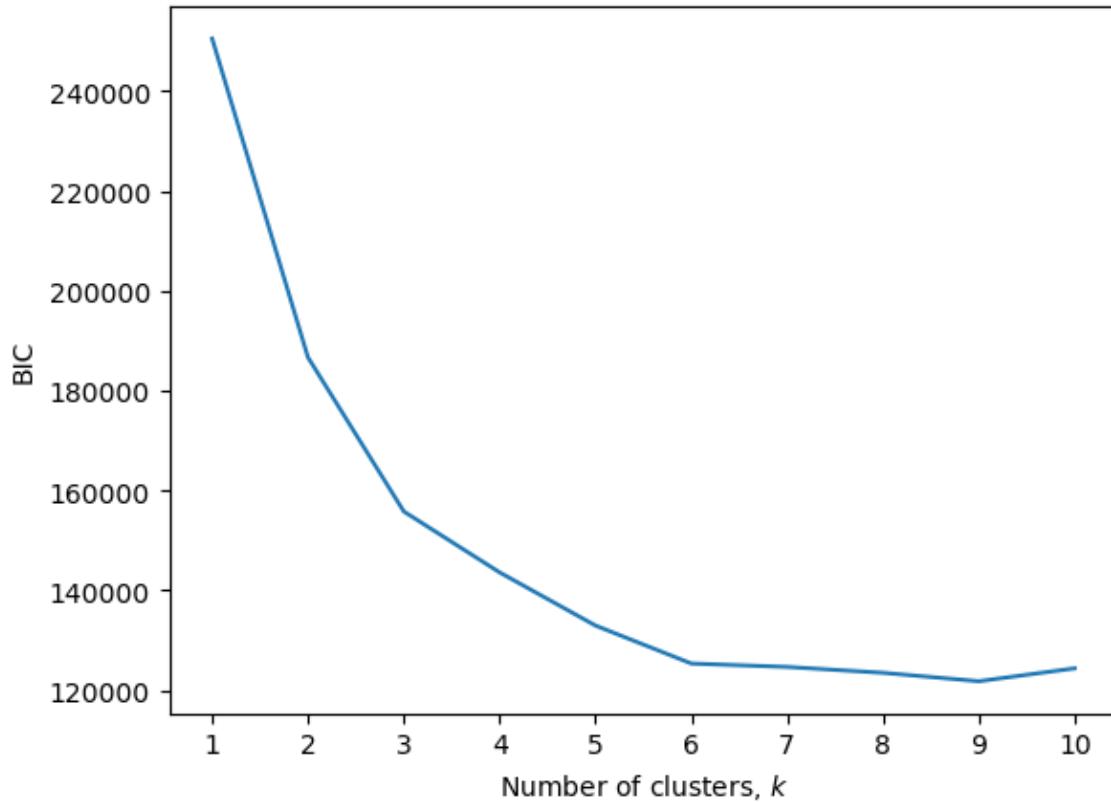


Using BIC method to find the proper number of clusters

In [37]:

```
ks = np.arange(1,11)
bics = []
for k in ks:
    gmm = mixture.GaussianMixture(n_components=k, covariance_type='full')
    gmm.fit(F_Result_LSTM)
    bics.append(gmm.bic(F_Result_LSTM))

# Plot the data
fig, ax = plt.subplots()
ax.plot(ks, bics)
ax.set_xlabel(r'Number of clusters, $k$')
ax.set_ylabel('BIC')
ax.set_xticks(ks);
```



2D Plot

In [38]:

```
F_Result_LSTM.shape
```

Out[38]:

```
(41166, 2)
```

In [39]:

```
df_FR_2d_LSTM = pd.DataFrame(F_Result_LSTM)
df_FR_2d_LSTM.columns = ['x', 'y']
df_FR_2d_LSTM.head()
```

Out[39]:

	x	y
0	-0.195539	-1.592148
1	2.816493	0.385995
2	-0.633428	1.402577
3	-0.755334	1.242345
4	2.695727	0.276364

In [40]:

```
Model = KMeans(n_clusters=5, init='k-means++', max_iter=1000)
Model.fit(df_FR_2d_LSTM)
```

C:\Users\user\anaconda3\lib\site-packages\sklearn\cluster_kmeans.py:870:
 FutureWarning: The default value of `n_init` will change from 10 to 'auto'
 in 1.4. Set the value of `n_init` explicitly to suppress the warning
 warnings.warn(

Out[40]:

KMeans(max_iter=1000, n_clusters=5)

In a Jupyter environment, please rerun this cell to show the HTML representation or
 trust the notebook.

On GitHub, the HTML representation is unable to render, please try loading this page
 with nbviewer.org.

In [41]:

```
df_FR_2d_LSTM['Cluster'] = Model.fit_predict(df_FR_2d_LSTM)
df_FR_2d_LSTM['labels'] = Model.labels_
centroids = Model.cluster_centers_
df_FR_2d_LSTM.head()
```

C:\Users\user\anaconda3\lib\site-packages\sklearn\cluster_kmeans.py:870:
 FutureWarning: The default value of `n_init` will change from 10 to 'auto'
 in 1.4. Set the value of `n_init` explicitly to suppress the warning
 warnings.warn(

Out[41]:

	x	y	Cluster	labels
0	-0.195539	-1.592148	2	2
1	2.816493	0.385995	0	0
2	-0.633428	1.402577	1	1
3	-0.755334	1.242345	1	1
4	2.695727	0.276364	0	0

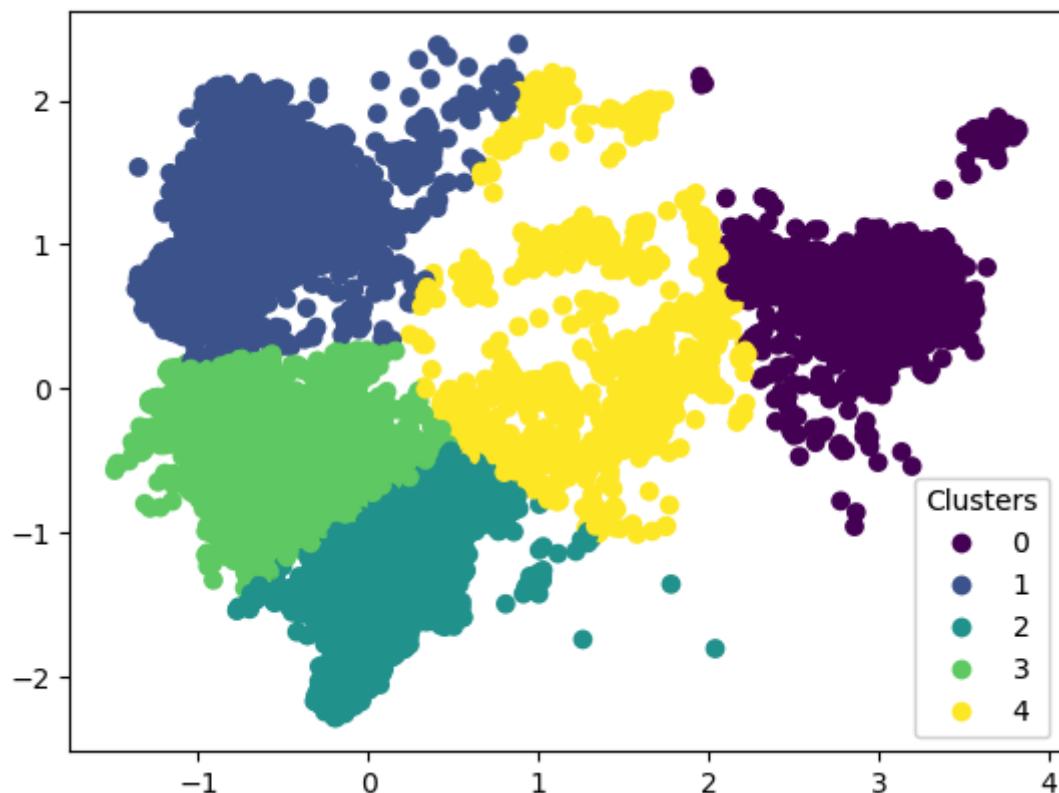
In [73]:

```
fig, ax = plt.subplots()

scatter = ax.scatter(df_FR_2d_LSTM[ 'x' ]
                     ,df_FR_2d_LSTM[ 'y' ],
                     c=df_FR_2d_LSTM[ 'Cluster' ]
                     )

legend1 = ax.legend(*scatter.legend_elements(num='auto'),
                    loc="lower right",
                    title="Clusters")

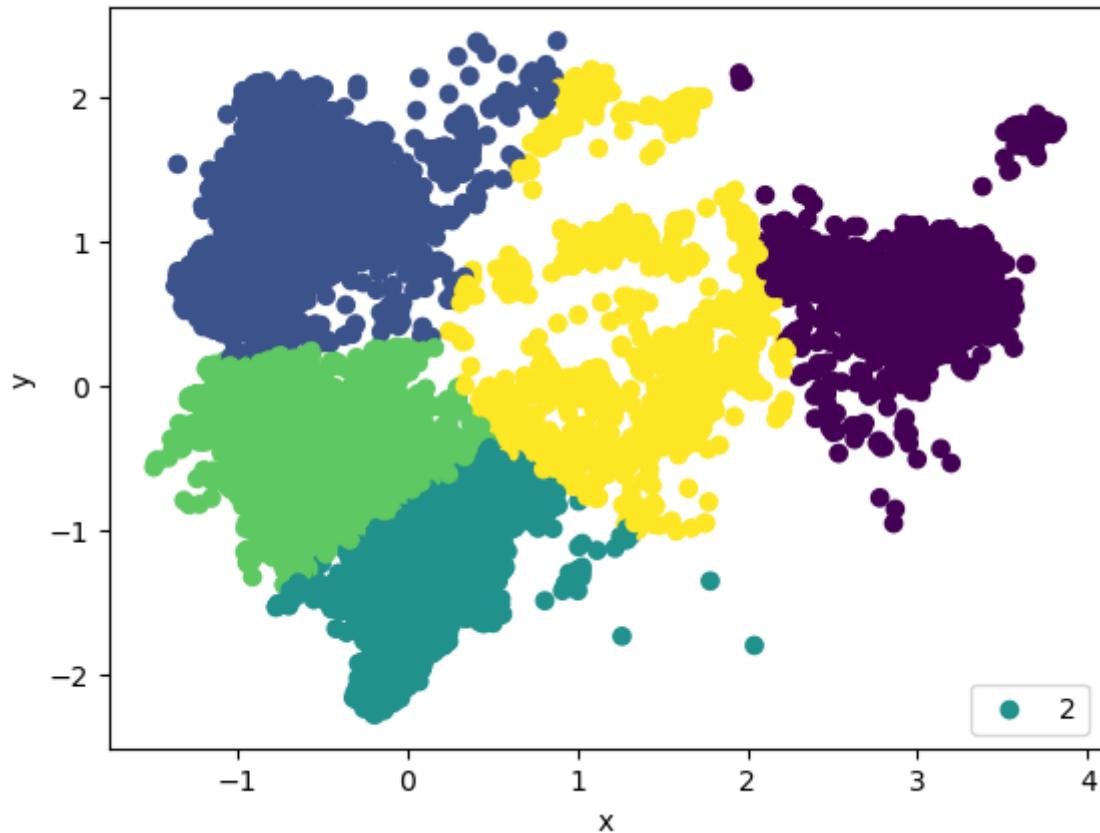
ax.add_artist(legend1)
plt.show()
```



In [69]:

```
plt.scatter(df_FR_2d_LSTM['x'], df_FR_2d_LSTM['y'], c=df_FR_2d_LSTM['Cluster'])
plt.ylabel('y')
plt.xlabel('x')
plt.legend(df_FR_2d_LSTM['Cluster'],
           ,loc='lower right')

# plt.Legend(['Cludster_1',
#             'Cluster_2',
#             'Cluster_3',
#             'Cluster_4',
#             'Cluster_5']
#            ,Loc='Lower right'
#            )
plt.show()
```



3D Plot

In [43]:

```
pca_3d = PCA(n_components=3)
```

In [44]:

```
Result_LSTM.shape
```

Out[44]:

```
(41166, 5, 16)
```

In [45]:

```
Result_1_LSTM.shape
```

Out[45]:

```
(41166, 80)
```

In [46]:

```
F_Result_3d_LSTM = pca_3d.fit_transform(Result_1_LSTM)
```

In [47]:

```
pca_3d.explained_variance_ratio_
```

Out[47]:

```
array([0.4172846 , 0.3285278 , 0.05525877], dtype=float32)
```

In [48]:

```
F_Result_3d_LSTM.shape
```

Out[48]:

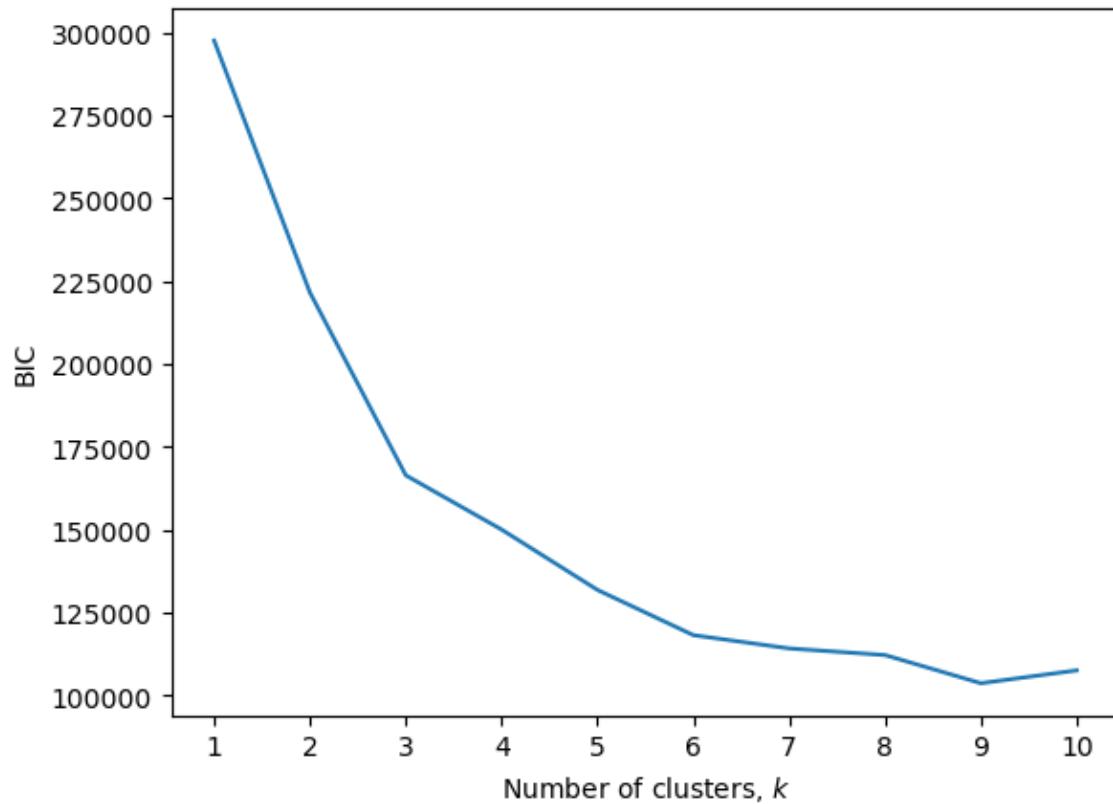
```
(41166, 3)
```

Number of clusters

In [49]:

```
ks = np.arange(1,11)
bics = []
for k in ks:
    gmm = mixture.GaussianMixture(n_components=k, covariance_type='full')
    gmm.fit(F_Result_3d_LSTM)
    bics.append(gmm.bic(F_Result_3d_LSTM))

# Plot the data
fig, ax = plt.subplots()
ax.plot(ks, bics)
ax.set_xlabel(r'Number of clusters, $k$')
ax.set_ylabel('BIC')
ax.set_xticks(ks);
```



In [50]:

```
# Creating DataFrame
df_FR_3d_LSTM = pd.DataFrame(F_Result_3d_LSTM)
df_FR_3d_LSTM.columns = ['x', 'y', 'z']
df_FR_3d_LSTM.head()
```

Out[50]:

	x	y	z
0	-0.195546	-1.592167	0.355916
1	2.816493	0.385994	-0.305002
2	-0.633427	1.402577	0.029464
3	-0.755333	1.242345	0.058242
4	2.695728	0.276362	-0.273730

In [51]:

```
# Working with 8 clusters
Model2 = KMeans(n_clusters=6, init='k-means++', max_iter=1000)
Model2.fit(df_FR_3d_LSTM)
```

C:\Users\user\anaconda3\lib\site-packages\sklearn\cluster_kmeans.py:870:
FutureWarning: The default value of `n_init` will change from 10 to 'auto'
in 1.4. Set the value of `n_init` explicitly to suppress the warning
warnings.warn(

Out[51]:

KMeans(max_iter=1000, n_clusters=6)

In a Jupyter environment, please rerun this cell to show the HTML representation or
trust the notebook.

On GitHub, the HTML representation is unable to render, please try loading this page
with nbviewer.org.

In [52]:

```
df_FR_3d_LSTM['Cluster'] = Model2.fit_predict(df_FR_3d_LSTM)
df_FR_3d_LSTM['labels'] = Model2.labels_
centroids = Model2.cluster_centers_
df_FR_3d_LSTM.head()
```

C:\Users\user\anaconda3\lib\site-packages\sklearn\cluster_kmeans.py:870:
FutureWarning: The default value of `n_init` will change from 10 to 'auto'
in 1.4. Set the value of `n_init` explicitly to suppress the warning
warnings.warn(

Out[52]:

	x	y	z	Cluster	labels
0	-0.195546	-1.592167	0.355916	1	1
1	2.816493	0.385994	-0.305002	2	2
2	-0.633427	1.402577	0.029464	0	0
3	-0.755333	1.242345	0.058242	0	0
4	2.695728	0.276362	-0.273730	2	2

Graph

In [53]:

```
#df_FR_3d['Labels'] = Labels

trace = go.Scatter3d(
    x = df_FR_3d_LSTM['x'],
    y = df_FR_3d_LSTM['y'],
    z = df_FR_3d_LSTM['z'],
    mode = 'markers',
    marker=dict(color=df_FR_3d_LSTM['Labels'], size = 5, line=dict(color
))

data = [trace]
layout = go.Layout(
    title='Clusters',
    scene= dict(
        xaxis = dict(title = 'x'),
        yaxis = dict(title = 'y'),
        zaxis = dict(title = 'z'))
)

fig = go.Figure(data=data, layout=layout)
py.offline.iplot(fig)
plt.show()
```

In []: